

Statistical inference with incomplete and high-dimensional data—modeling polytraumatized patients

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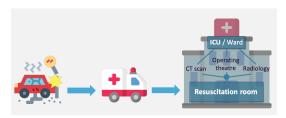


TraumaBase project: decision support for patients

• 20000 trauma patients + 250 measurements variables

Center	Accident	Age	Sex	Lactactes	BP	Shock	Platelet	
Beaujon	fall	54	m	NA	180	yes	292000	
Pitie	gun	26	m	NA	131	no	323000	
Beaujon	moto	63	m	3.9	NA	yes	318000	
Pitie	moto	30	f	NA	107	no	211000	
HEGP	knife	16	m	2.5	118	no	184000	

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Management scheme of a traumatized patient.

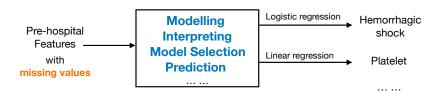


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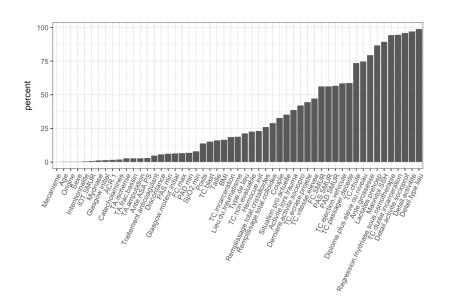
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Objective: help the clinicians make decisions





TraumaBase: percentage of missing values



List-wise deletion?

"One of the ironies of Big Data is that missing data play an ever more significant role." (Samworth, 2019)

Example

A $n \times p$ dataset, each entry has a probability 1% to be missing independently.

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Example

A $n \times p$ dataset, each entry has a probability 1% to be missing independently.

•
$$p = 5 \xrightarrow{\text{List-wise}} 95\%$$
 rows kept

•
$$p = 300 \xrightarrow{\text{List-wise}} 5\%$$
 rows kept

⇒ List-wise deletion impossible



Literature on missing values

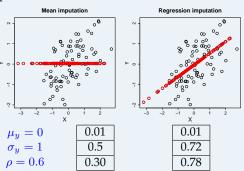
- R-miss-tastic: resource website for managing missing data, 150 packages (most based on imputation)
- Books: Schafer (2002), Little & Rubin (2019); Kim & Shao (2013);
 Carpenter & Kenward (2013); Stef van Buuren (2018)

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Single imputation

Example: $(x_i, y_i) \sim \mathcal{N}(\mu, \Sigma)$ *i.i.d.*, 70% missing entries on y randomly **Aim:** Estimate parameters & their variance



⇒ have bias & fail to evaluate the uncertainty caused by NA



Recommended method 1: multiple imputation

Example:

X_1	X_2	X_3	Y
NA	20	10	1
-6	45	NA	1
0	NA	30	0
NA	32	35	1
1	63	40	1
-2	NA	12	0

 \Rightarrow logistic regression with parameter β



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 \Rightarrow logistic regression with parameter β

1 Generate *M* plausible values for each missing entry

X_1	X_2	X_3	Y
3	20	10	1
-6	45	6	1
0	4	30	0
-4	32	35	1
1	63	40	1
-2	15	12	0

X_1	X_2	X_3	Y
-7	20	10	1
-6	45	9	1
0	12	30	0
13	32	35	1
1	63	40	1
-2	10	12	0

X_1	X_2	X_3	Y
7	20	10	1
-6	45	12	1
0	-5	30	0
2	32	35	1
1	63	40	1
-2	20	12	0

② Perform the analysis on each imputed data set: $\hat{\beta}_m$, $\widehat{Var}\left(\hat{\beta}_m\right)$

3 Combine the results (Rubin's rules):

$$\hat{\beta} = \frac{1}{M} \sum_{m=1}^{M} \hat{\beta}_m \qquad \hat{V} = \frac{1}{M} \sum_{m=1}^{M} \widehat{Var} \left(\hat{\beta}_m \right) + \frac{1 + \frac{1}{M}}{M - 1} \sum_{m=1}^{M} \left(\hat{\beta}_m - \hat{\beta} \right)^2$$



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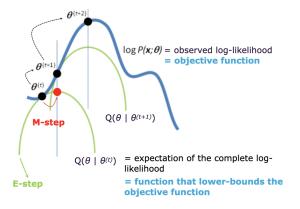
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- + Variability of missing values is taken into account
- Aggregating different models from multiple imputed data is complex



Recommended method 2: EM algorithm

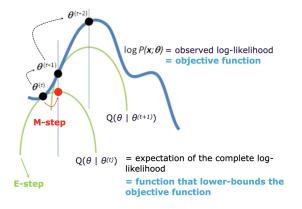
Modify the estimation process to deal with missing values. **Maximum observed likelihood:** EM algorithm to obtain point estimates + Supplemented EM (Meng & Rubin, 1991) for their variability





Recommended method 2: EM algorithm

Modify the estimation process to deal with missing values. **Maximum observed likelihood:** EM algorithm to obtain point estimates + Supplemented EM (Meng & Rubin, 1991) for their variability



- + Perfectly dedicated toward the problem (ML estimates)
- One specific algorithm for each statistical method
- Not many implementations even for simple models (e.g. logistic regression)
- Not a complete methodology

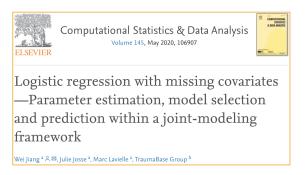
Objectives and contributions

- Complete methodologies for estimation, model selection and prediction (few competitors) with missing data
 - Classical setting (n > p): logistic regression (SAEM)
 - High dimension (*p* > *n*): parametric & non-parametric regression (FDR control)
- Software packages
 - Implementation of R packages
 - Numerical experiments
- Application to the medical dataset—TraumaBase
 - Predict the risk of hemorrhagic shock
 - Predict platelet levels

Contribution 1:

Logistic regression with missing covariates

(Jiang, Josse, Lavielle, TraumaBase, 2020)





Logistic regression model

$$X = (x_{ij})$$
 a $n \times p$ matrix of quantitative covariates $y = (y_i)$ an n -vector of binary responses $\{0, 1\}$

Logistic regression model

$$\mathbb{P}(y_i = 1 | X_i; \beta) = \frac{\exp(\beta_0 + \sum_{j=1}^p \beta_j x_{ij})}{1 + \exp(\beta_0 + \sum_{j=1}^p \beta_j x_{ij})}$$

Covariates

$$X_i \sim \mathcal{N}_p(\mu, \Sigma)$$

Log-likelihood for complete-data with the set of parameters $\theta = (\mu, \Sigma, \beta)$

$$\ell(\theta; X, y) = \sum_{i=1}^{n} \Big(\log(p(y_i|X_i; \beta)) + \log(p(X_i; \mu, \Sigma)) \Big).$$



Missing data mechanisms

$$\begin{aligned} & \text{Decomposition: } X = (X_{\text{obs}}, X_{\text{mis}}). \\ & \text{Pattern of missingness: } R \text{ with } R_{ij} = \begin{cases} 1, & \text{if } X_{ij} \text{ is observed;} \\ 0, & \text{otherwise.} \end{cases} \end{aligned}$$

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Missing completely at random (MCAR)

$$p(R \mid X) = p(R)$$
 e.g. Data lost when merging databases

Missing at random (MAR)

$$p(R \mid X) = p(R \mid X_{obs})$$
 e.g. Blood pressure not collected at larger probability in traffic accident.

Missing not at random (MNAR)

$$p(R \mid X) = p(R \mid X_{\rm obs}, X_{\rm mis}) \quad \textit{e.g.} \ \, \frac{\text{Blood pressure}}{\text{probability when its value}} < 90 \, \text{mmHg}.$$

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Assumption: Missing data are Missing at Random

⇒ Ignore modeling missing mechanism

EM algorithm with missing data

Observed-data likelihood

Aim: $\arg \max_{\theta} \ell(\theta; X_{\text{obs}}, y) = \int \ell(\theta; X, y) dX_{\text{mis}}.$

EM:

• **E-step:** Evaluate the quantity

Complete-data likelihood $X_{\mathrm{obs}},y; heta_{k-1}]$

$$Q_k(\theta) = \mathbb{E}[\ell(\theta; X, y) | X_{\text{obs}}, y; \theta_{k-1}]$$
$$= \int \ell(\theta; X, y) p(X_{\text{mis}} | X_{\text{obs}}, y; \theta_{k-1}) dX_{\text{mis}}.$$

• **M-step:** $\theta_k = \arg \max_{\theta} Q_k(\theta)$.



EM algorithm with missing data

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Unfeasible computation of expectation!

MCEM (Wei & Tanner 1990): Generate a large set of samples of missing data from $p(X_{mis}|X_{obs},y;\theta_{k-1})$ and replaces the expectation by an empirical mean.

EM algorithm with missing data

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Unfeasible computation of expectation!

MCEM (Wei & Tanner 1990): Generate a large set of samples of missing data from $p(X_{\text{mis}}|X_{\text{obs}},y;\theta_{k-1})$ and replaces the expectation by an empirical mean.

Require a huge number of samples to converge!

Stochastic Approximation EM

(book, Lavielle 2014) Starting from an initial guess θ_0 , the kth iteration consists of three steps:

• **Simulation:** For $i=1,2,\cdots,n$, draw one sample $X_{i,\mathrm{mis}}^{(k)}$ from $\mathrm{p}(X_{i,\mathrm{mis}}|X_{i,\mathrm{obs}},y_i;\theta_{k-1}).$

Stochastic approximation: Update the function Q

$$Q_k(\theta) = Q_{k-1}(\theta) + \gamma_k \left(\ell(\theta; X_{\text{obs}}, X_{\text{mis}}^{(k)}, y) - Q_{k-1}(\theta) \right),$$

where (γ_k) is a decreasing sequence of positive numbers.

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Convergence: (Allassonniere et al. 2010)

The choice of the sequence (γ_k) is important for ensuring the almost sure convergence of SAEM to a MLE.



Metropolis-Hastings algorithm

Target distribution

$$f_i(X_{i,\text{mis}}) = p(X_{i,\text{mis}}|X_{i,\text{obs}}, y_i; \theta)$$

$$\propto p(y_i|X_i; \beta) p(X_{i,\text{mis}}|X_{i,\text{obs}}; \mu, \Sigma).$$



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Proposal distribution $g_i(X_{i,\mathrm{mis}}) = \mathrm{p}(X_{i,\mathrm{mis}}|X_{i,\mathrm{obs}};\mu,\Sigma)$

$$X_{i,\mathrm{mis}}|X_{i,\mathrm{obs}} \sim \mathcal{N}_p(\mu_i,\Sigma_i)$$

$$\mu_i = \mu_{i,\mathrm{mis}} + \Sigma_{i,\mathrm{mis},\mathrm{obs}}\Sigma_{i,\mathrm{obs},\mathrm{obs}}^{-1}(X_{i,\mathrm{obs}} - \mu_{i,\mathrm{obs}}),$$

$$\Sigma_i = \Sigma_{i,\mathrm{mis},\mathrm{mis}} - \Sigma_{i,\mathrm{mis},\mathrm{obs}}\Sigma_{i,\mathrm{obs},\mathrm{obs}}^{-1}\Sigma_{i,\mathrm{obs},\mathrm{obs}}^{-1}\Sigma_{i,\mathrm{obs},\mathrm{mis}},$$

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Metropolis:

$$oldsymbol{0}$$
 $oldsymbol{z}_{im}^{(k)} \sim g_i(oldsymbol{x}_{i,mis})$, $u \sim \mathcal{U}[0,1]$

$$r = \frac{f_i(\mathbf{z}_{im}^{(k)})/g_i(\mathbf{z}_{im}^{(k)})}{f_i(\mathbf{z}_{i,m-1}^{(k)})/g_i(\mathbf{z}_{i,m-1}^{(k)})}$$

Only need a few steps of Markov chains in each iteration of SAEM.

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3 If
$$u < r$$
, accept $z_{im}^{(k)}$

Only need a few steps of Markov chains in each iteration of SAEM.

Variance estimation:

Given the MH samples of unobserved data, and the SAEM estimate ⇒ Estimate **observed Fisher information** by empirical means.



Model selection: criterion BIC

With \tilde{p}_{θ} the number of estimated parameters in a given model \mathcal{M} , model selection criterion (**penalized likelihood**):

$$BIC(\mathcal{M}) = -2\ell(\hat{\theta}_{\mathcal{M}}; X_{obs}, y) + \log(n)d(\mathcal{M}),$$

How to estimate **observed likelihood**?

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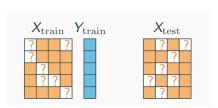
How to estimate **observed likelihood**?

$$\begin{split} \mathbf{p}(y_i, X_{i, \text{obs}}; \theta) &= \int \mathbf{p}(y_i, X_{i, \text{obs}} | X_{i, \text{mis}}; \theta) \mathbf{p}(X_{i, \text{mis}}; \theta) dX_{i, \text{mis}} \\ &= \int \mathbf{p}(y_i, X_{i, \text{obs}} | X_{i, \text{mis}}; \theta) \frac{\mathbf{p}(X_{i, \text{mis}}; \theta)}{g_i(X_{i, \text{mis}})} g_i(X_{i, \text{mis}}) dX_{i, \text{mis}} \\ &= \mathbb{E}_{g_i} \left(\mathbf{p}(y_i, X_{i, \text{obs}} | X_{i, \text{mis}}; \theta) \frac{\mathbf{p}(X_{i, \text{mis}}; \theta)}{g_i(X_{i, \text{mis}})} \right). \end{split}$$

Sample from g_i (the proposal distribution in SAEM) \Rightarrow Empirical mean.

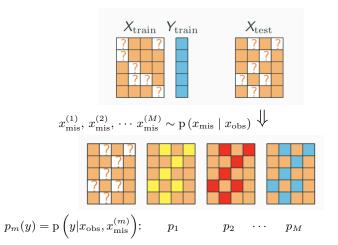


Prediction: missing values in test set





Prediction: missing values in test set



$$\hat{y} = \underset{y}{\operatorname{arg max}} p(y|x_{\text{obs}}) = \underset{y}{\operatorname{arg max}} \sum_{m=1}^{M} p_m(y)$$



Method comparison: estimates & coverage

$$x$$
: $p = 5$, $n = 10\,000$; $y \in \{0, 1\}$ percentage of missingness = 10% 1000 replicates

Figure: Estimation bias of $\hat{\beta}_3$.

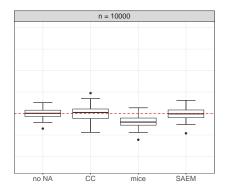


Table: Coverage of confidence interval.

	no NA	CC	mice	SAEM
β_0	95.2	94.4	95.2	94.9
β_1	96.0	94.7	93.9	95.1
β_2	95.5	94.6	94.0	94.3
β_3	94.9	94.3	86.5	94.7
β_4	94.6	94.2	96.2	95.4
β_5	95.9	94.4	89.6	94.7
β_3 β_4	94.9 94.6	94.3 94.2	86.5 96.2	94 95



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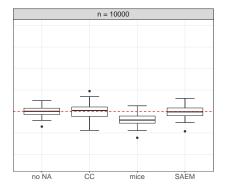


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β_3	94.9	94.3	86.5	94.7
β_4	94.6	94.2	96.2	95.4
β_5	95.9	94.4	89.6	94.7

Extended simulations:

- Robustness (model-misspecification)
- Percentage of missingness
- Separability of classes



Application on TraumaBase

Variables

Age Weight

Weight Height

BMI

Glasgow

Motor Glasgow Pulse Pressure min

Pulse Pressure at

arrival

Heart Rate at arrival

Hb Hemocue

SpO₂ Volume Expander

colloids Volume Expander crystalloids. • 6384 patients

14 continuous variables

Logistic regression with missing values



Hemorrhagic shock

$$P(y=1 \mid X; \hat{\beta}) ?$$

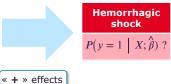


Application on TraumaBase

Variables	Effect	Estimate (std error)
Age	+	0.011 (0.0033)
Weight		
Height		
BMI		
Glasgow		
Motor Glasgow	-	-0.16 (0.036)
Pulse Pressure min	-	-0.025 (0.0050)
Pulse Pressure at arrival	-	-0.021 (0.0056)
Heart Rate max	+	0.026 (0.0025)
Heart Rate at arrival		
Hb Hemocue	-	-0.23 (0.031)
SpO₂		
Volume Expander colloids	+	0.0019 (0.00021)
Volume Expander crystalloids.	+	0.00090 (0.00010)



 A low Glasgow score means one makes no motor response, often in the case of hemorrhagic shock.

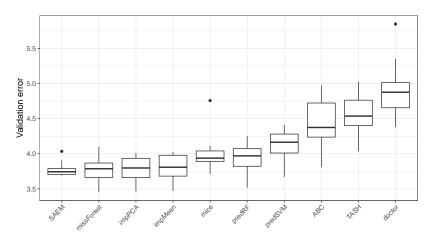


 Older people tend to have a larger possibility to suffer from hemorrhagic shock.



Predictive performance

Random split: training set (70%) + test set (30%) (repeated 15 times)



False Negative costs 10 times more than False Positive ⇒ Threshold





misaem: Linear Regression and Logistic Regression with Missing

Estimate parameters of linear regression and logistic regression with missing covariates with missing data, perform model selection and prediction, using EM-type algorithms.

 CRAN
 Version:
 1.0.0

 Mirrors
 Depends:
 R (≥ 3.4.0)

Parameter estimation:

miss.glist = miss.glm(y~., data = df, maxruns = 500) summary(miss.glist)





misaem: Linear Regression and Logistic Regression with Missing Covariates

Estimate parameters of linear regression and logistic regression with missing covariates with missing data, perform model selection and prediction, using EM-type algorithms.

Version: 1.0.0

CRAN Depends: $R (\ge 3.4.0)$

Parameter estimation:

 $miss.glist = miss.glm(y^{-}, data = df, maxruns = 500)$ summary(miss.glist)

Model selection with BIC:

miss.model = miss.glm.model.select(y, X) print(miss.model)



CRAN

Mirrors

misaem: Linear Regression and Logistic Regression with Missing Covariates

Estimate parameters of linear regression and logistic regression with missing covariates with missing data, perform model selection and prediction, using EM-type algorithms.

Version: 1.0.0

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pr.saem <- predict(miss.model, X.test)</pre>





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Estimate parameters of linear regression and logistic regression with missing covariates with missing data, perform model selection and prediction, using EM-type algorithms.

CRAN Mirrors Version: 1.0.0 Depends: R (≥ 3.4.0)

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Model selection with BIC:

miss.model = miss.glm.model.select(y, X) print(miss.model)

Prediction on (incomplete) test set:

pr.saem <- predict(miss.model, X.test)</pre>

Also provide solutions for linear regression with missing values:

miss.list = miss.lm(y~., data = df)

Contribution 2:

Variable selection for high-dimensional incomplete data

(Jiang, Bogdan, Josse, Miasojedow, Rockova, 2019)





Model selection in high-dimension



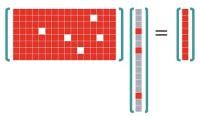
Model selection in high-dimension

Linear regression model: $y = X\beta + \varepsilon$,

$$y \in \mathbb{R}^n$$
, $X \in \mathbb{R}^{n \times p}$, $\varepsilon \sim \mathcal{N}(0, \sigma^2 I_n)$

Assumptions:

- high-dimension: p large (including $p \ge n$)
- β is sparse with k < n nonzero coefficients



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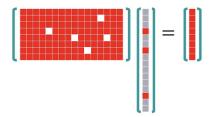
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Assumptions:

- high-dimension: p large (including $p \ge n$)
- β is sparse with k < n nonzero coefficients



Aims:

- Model selection with FDR control
- Parameter estimation with less bias
- Managing missing values



l_1 penalization methods (complete data)

• LASSO (Tibshirani, 1996)

$$\hat{\beta}_{LASSO} = \underset{\beta \in \mathbb{R}^p}{\arg \min} \frac{1}{2} ||y - X\beta||^2 + \lambda ||\beta||_1,$$

detects important variables with high probability but includes many false positives.

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$$\hat{\beta}_{SLOPE} = \operatorname*{arg\,min}_{\beta \in \mathbb{R}^p} \frac{1}{2} \|y - X\beta\|^2 + \sigma \sum_{j=1}^p \lambda_j |\beta|_{(j)},$$

where
$$\lambda_1 \geq \lambda_2 \geq \cdots \geq \lambda_p \geq 0$$
 and $|\beta|_{(1)} \geq |\beta|_{(2)} \geq \cdots \geq |\beta|_{(p)}$.



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where
$$\lambda_1 \geq \lambda_2 \geq \cdots \geq \lambda_p \geq 0$$
 and $|\beta|_{(1)} \geq |\beta|_{(2)} \geq \cdots \geq |\beta|_{(p)}$.

To control **False Discovery Rate (FDR)** at level *q*:

$$\lambda_{BH}(j) = \phi^{-1}(1 - q_j), \quad q_j = \frac{jq}{2p}, \quad X^T X = I, \quad \text{ther}$$

$$FDR = \mathbb{E}\left[\frac{\# \text{False rejections}}{\# \text{Rejections}}\right] \leq q$$



Bayesian SLOPE (complete data)

Problem: λ for SLOPE leading to FDR control are typically large. SLOPE often returns **an inconsistent estimation.**

 \Rightarrow improve?



Bayesian SLOPE (complete data)

Problem: λ for SLOPE leading to FDR control are typically large. SLOPE often returns **an inconsistent estimation**.

$$\Rightarrow$$
 improve?

SLOPE estimate = MAP of a Bayesian regression with SLOPE prior.

$$\hat{\beta}_{SLOPE} = \mathop{\arg\max}_{\beta} \mathsf{p}(y \mid X, \beta, \sigma^2; \lambda) \propto \mathsf{p}(y \mid X, \beta) \mathsf{p}(\beta \mid \sigma^2; \lambda)$$

where the SLOPE prior:

$$p(\beta \mid \sigma^2; \lambda) \propto \prod_{j=1}^p \exp\left(-\frac{1}{\sigma}\lambda_j |\beta|_{(j)}\right)$$



Adaptive Bayesian SLOPE (complete data)

We propose an adaptive version of Bayesian SLOPE (ABSLOPE), with the prior for β as

$$\mathrm{p}(\beta \mid \gamma, c, \sigma^2; \lambda) \propto c^{\sum_{j=1}^p \mathbb{I}(\gamma_j = 1)} \prod_j \exp\left\{ -\frac{\mathbf{w}_j}{|\beta_j|} \frac{1}{\sigma} \lambda_{r(\mathbf{W}\beta, j)} \right\},$$

Interpretation of the model:

- β_j is large enough \Rightarrow true signal; $0 \Rightarrow$ noise.
- $\gamma_j \in \{0,1\}$ signal indicator. $\gamma_j | \theta \sim Bernoulli(\theta)$ and θ the sparsity.
- $c \in [0, 1]$: the inverse of average signal magnitude.
- $W = \operatorname{diag}(w_1, w_2, \cdots, w_p)$ and its diagonal element:

$$w_j = c\gamma_j + (1 - \gamma_j) = \begin{cases} c, & \gamma_j = 1\\ 1, & \gamma_j = 0 \end{cases}$$

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Adaptive Bayesian SLOPE (complete data)

Advantage of introducing W:

- when $\gamma_j=0$, $w_j=1$, i.e., the null variables are treated with the regular SLOPE penalty
- when $\gamma_j = 1$, $w_j = c < 1$, i.e, smaller penalty $\lambda_{r(W\beta,j)}$ for true predictors than the regular SLOPE one

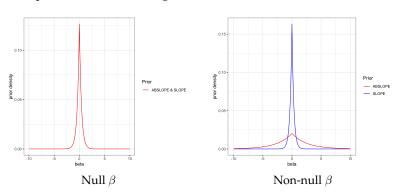
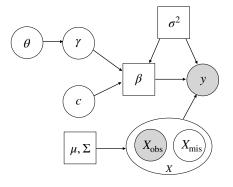


Figure: comparison of SLOPE prior and ABSLOPE prior



Modeling with missingness

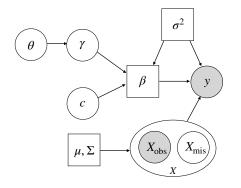
Decomposition: $X = (X_{\rm obs}, X_{\rm mis})$





Modeling with missingness

Decomposition: $X = (X_{\text{obs}}, X_{\text{mis}})$



$$\ell_{\text{comp}} = \log p(y, X, \gamma, c; \beta, \theta, \sigma^2) + pen(\beta)$$

= \log \{p(X; \mu, \Sigma) p(y | X; \beta, \sigma^2) p(\gamma; \theta) p(c)\} + pen(\beta)

Objective: Maximize $\ell_{\text{obs}} = \iiint \ell_{\text{comp}} dX_{\text{mis}} dc d\theta d\gamma$.

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Adapted SAEM algorithm

- E step:
 - $Q^t = \mathbb{E}(\ell_{\text{comp}}) \quad \text{wrt} \quad p(X_{\text{mis}}, \gamma, c, \theta \mid y, X_{\text{obs}}, \beta^t, \sigma^t, \mu^t, \Sigma^t).$
 - Simulation: draw one sample $(X_{\min}^t, \gamma^t, c^t, \theta^t)$ from

$$\begin{aligned} &\mathbf{p}(X_{\mathrm{mis}}, \gamma, c, \theta \mid y, X_{\mathrm{obs}}, \beta^{t-1}, \sigma^{t-1}, \mu^{t-1}, \Sigma^{t-1}); \\ &\mathbf{[Gibbs \ sampling]} \end{aligned}$$

• Stochastic approximation: update function Q with

$$Q^{t} = Q^{t-1} + \eta_{t} \left(\ell_{\text{comp}} \Big|_{X_{\text{mis}}^{t}, \gamma^{t}, c^{t}, \theta^{t}} - Q^{t-1} \right).$$

• M step: $\beta^t, \sigma^t, \mu^t, \Sigma^t = \arg \max Q^t$. [Proximal gradient descent, Shrinkage of covariance]

Details of initialization, generating samples and optimization are in arXiv:1909.06631



Shrinkage of covariance matrix

Estimation of covariance matrix Σ in high-dimension:

- In some special case, Σ is known.
- If given sparseness ⇒ graphical lasso
- But no additional knowledge of $\Sigma \Rightarrow$ shrinkage estimation. Optimal linear shrinkage (Ledoit and Wolf, 2012):

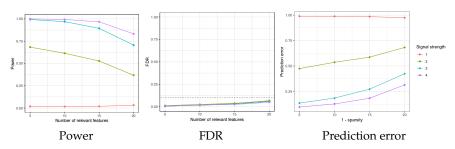
$$\hat{\Sigma} = \rho_1 I + \rho_2 S$$
, where $\rho_1, \rho_2 = \underset{\rho_1, \rho_2}{\arg \min} \mathbb{E} ||\hat{\Sigma} - \Sigma||^2$.

 \Rightarrow shrink the empirical eigenvalues towards their mean; ρ_1 and ρ_2 chosen by asymptotically uniformly minimum quadratic risk.



Simulation study (200 rep. \Rightarrow average)

n=p=100, no correlation and 10% missingness

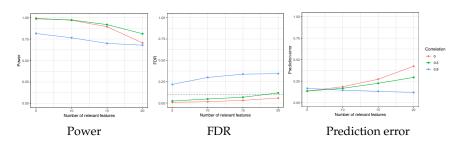


- FDR controlled at expected level 0.1.
- Power increases and estimation bias decreases if larger sparsity or stronger signal.



Simulation study (200 rep. \Rightarrow average)

with correlation



- FDR controlled with small correlation.
- Existence of correlation increases the prediction accuracy.

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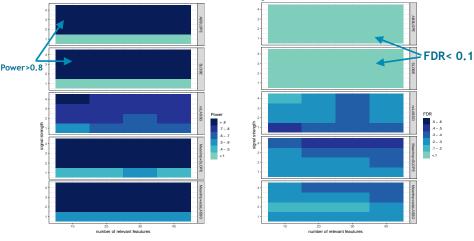
Method comparison (few competitors)

- ABSLOPE
- SLOBE: simplified version (conditional expectation instead of generating samples of latent variables)
- ncLASSO (Loh and Wainwright, 2012): LASSO with NA \Rightarrow Non-convex optimisation requires to know bound of $\|\beta\|_1 \Rightarrow$ difficult in practice
- Mean imputation followed by
 - SLOPE with known σ
 - adaptive LASSO (Zou, 2006)

In the SLOPE type methods, λ = BH sequence which controls the FDR at level **0.1**

Method comparison (200 rep. \Rightarrow average)

 500×500 dataset, 10% missingness, with correlation darker color = larger value.



• ABSLOPE & SLOBE: FDR control (<0.1) when signal strength >1

FDR

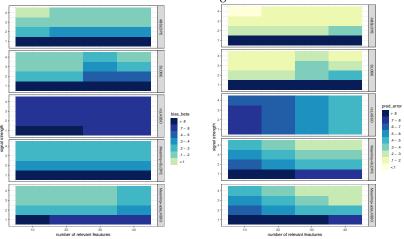
• Others: sacrifice FDR to achieve good power

Power

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Method comparison (200 rep. \Rightarrow average)

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Bias of β

Prediction error

 ABSLOPE: good performance, especially with larger sparsity and stronger signal strength.



Computational cost

Execution time (seconds)	n=p=100			n=p=500		
for one simulation	min	mean	max	min	mean	max
ABSLOPE	12.83	14.33	20.98	646.53	696.09	975.73
SLOBE	0.31	0.34	0.66	14.23	15.07	29.52
ncLASSO	16.38	20.89	51.35	91.90	100.71	171.00
MeanImp + SLOPE	0.01	0.02	0.09	0.24	0.28	0.53
MeanImp + LASSO	0.10	0.14	0.32	1.75	1.85	3.06

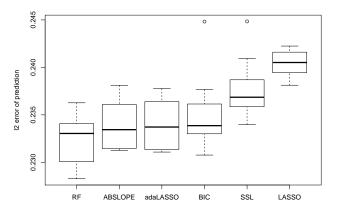
[Fast implementation: Parallel computing + Rcpp (C++)]



More on the real data

 $TraumaBase:\ Measurements \stackrel{Predict}{\longrightarrow} Platelet$

Cross-validation: random splits to training and test sets \times 10



- Comparable to random forest
- Interpretable model selection and estimation results



R package: ABSLOPE

ABSLOPE

R Package for "Adaptive Bayesian SLOPE --- High-dimensional Model Selection with Missing Values"

(2019, Bogdan M., Jiang W., Josse J., Miasojedow B., Rockova V.)

Languages

- R 90.2%
- C++ 9.8%

Main algorithm:

```
lambda = create_lambda_bhq(ncol(X),fdr=0.10)
list.res = ABSLOPE(X, y, lambda)
```



R package: ABSLOPE

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A fast and simplified algorithm (C++):

list.res.slobe = SLOBE(X, y, lambda)

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A fast and simplified algorithm (C++):

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Coefficient and support recovery:

list.res\$beta list.res\$gamma

Contribution 3:

Controlled model selection with non-parametric regression model

(preprint, 2020)

MISSKNOCKOFF: CONTROLLED VARIABLE SELECTION WITH MISSING VALUES

WEI JIANG¹, SZYMON MAJEWSKI², MALGORZATA BOGDAN³, JULIE JOSSE¹, ASAF WEINSTEIN⁴

1. CMAP, ECOLE POLYTECHNIQUE & INBIA XPOP, FRANCE 2. UNIVERSITY OF WASAW, POLAND

3. UNIVERSITY OF WROCIAW, POLAND & LIJNN UNIVERSITY, SWEDEN 4. THE HERREW UNIVERSITY OF BROCIAW.



Model-X assumption (complete data)

Similar setting (High-dimensional sparse regression) and aim (FDR control) as ABSLOPE:

$$n \ i.i.d. \ \text{samples} \ (X_{i1}, X_{i2}, \cdots, X_{ip}, y_i)_{i=1}^n$$

$$y_i \mid (X_{i1}, \dots, X_{ip}) \stackrel{\text{ind.}}{\sim} P_{y\mid X}, \quad i = 1, \dots, n$$

but:

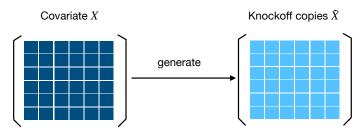
- Conditional distribution $P_{y|X}$ not specified (non-parametric)
- Distribution of *X* is known (model-X)



Knockoff method (complete data)

Non-parametric model selection with knockoff (Candes et al., 2018)

① Generate "fake" variables (without looking at *y*)



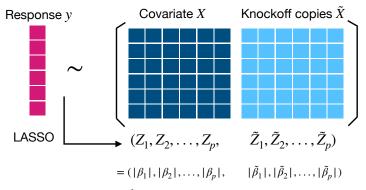
- Correlation between \tilde{X}_j and \tilde{X}_k = Correlation between X_j and X_k $(j \neq k)$
- Correlation between X_j and \tilde{X}_k = Correlation between X_j and X_k $(j \neq k)$
- ⇒ Knockoffs have same structure but all null.



Knockoff method (complete data)

Non-parametric model selection with **knockoff** (Candes et al., 2018)

- **①** Generate "fake" variables (without looking at *y*)
- Measure variable importance



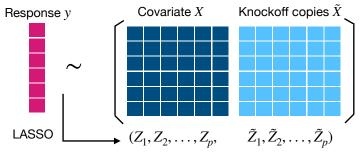
- Null variable: $Z_j \stackrel{d}{=} \tilde{Z}_j$
- Important variable: $Z_i >> \tilde{Z}_i$



Knockoff method (complete data)

Non-parametric model selection with knockoff (Candes et al., 2018)

- **①** Generate "fake" variables (without looking at *y*)
- Measure variable importance



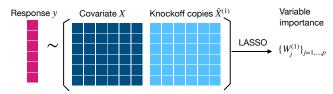
- Select variables more important than their knockoff copies:
 - Large $W_j = Z_j \tilde{Z}_j$
 - $W_i \ge \tau$ a threshold to control FDR at q:

$$\tau = \min \left\{ t > 0 : \frac{1 + \#\{j : W_j \le -t\}}{\#\{j : W_j \ge t\}} \right\}$$



Multiple knockoffs (complete data)

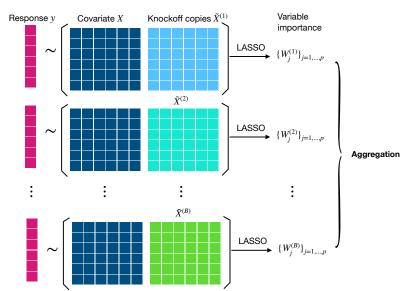
Single knockoff \rightarrow instability \Rightarrow Multiple knockoffs





Multiple knockoffs (complete data)

 $Single \ knockoff \rightarrow instability \Rightarrow Multiple \ knockoffs$

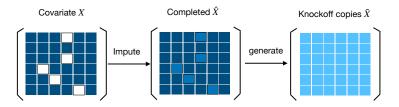




missKnockoff: single imputation

Contribution:

Combine single knockoff with single imputation

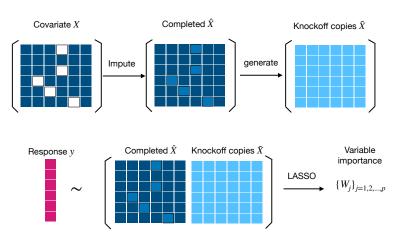




missKnockoff: single imputation

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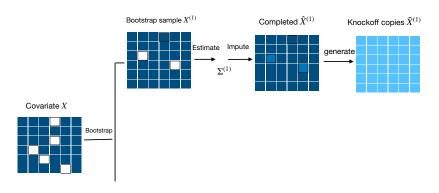


Contributions:

- Multiple imputation \Rightarrow single knockoff on each imputed dataset values
- Suggest new aggregation rules (inspired by multiple knockoffs)
- + take variability into account



Step1: Bootstrap *B* times



On each bootstrap sample, estimate the covariance (Schneider, 2001; Lounici et al., 2014):

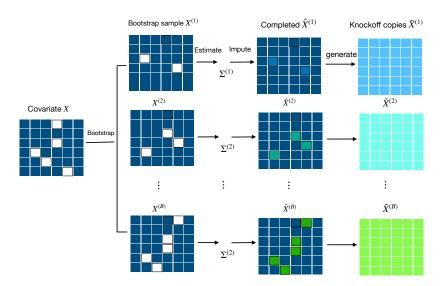
$$\Sigma^{(b)} = \left(\delta^{-1} - \delta^{-2}\right) \operatorname{diag}\left(\Sigma_n\right) + \delta^{-2}\Sigma_n \quad \Rightarrow \quad \operatorname{impute} \, \operatorname{p}(X_{\operatorname{mis}}|X_{\operatorname{obs}})$$

 δ : the proportion of observed entries

 Σ_n : the linear shrinkage estimation on empirical covariance of initially imputed dataset by 0.

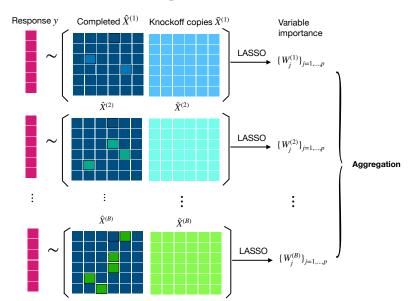


Step1: Bootstrap B times



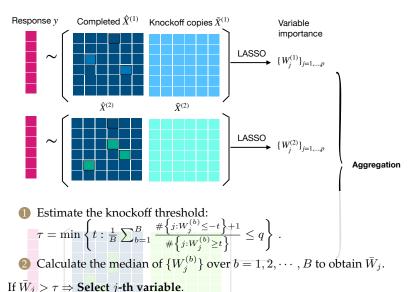


Step2: Measure variable importance





Step3: Aggregation by averaging the cases



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Theoretical result

Theorem (FDR control for single missKnockoff)

missKnockoff procedure with single imputation from $p(X_{mis}|X_{obs})$ controls FDR at level q.

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missKnockoff procedure with single imputation from $p(X_{mis}|X_{obs})$ controls FDR at level q.

Theorem (FDR estimation for multiple missKnockoff)

Consider the single missKnockoff procedure, which rejects $H_{0j}: \beta_j = 0$ if $W_j > t$, and let

$$FDR(t) = \mathbb{E}\left[\frac{\#\{j \in H_0 : W_j \ge t\}}{\#\{j : W_j \ge t\}}\right]$$
.

Then for the multiple missKnockoffs procedure with variable importance statistics $\{W_j^b\}$:

$$\mathbb{E}\left(\frac{1}{B}\sum_{b=1}^{B}\frac{\#\left\{j:W_{j}^{(b)}\leq-t\right\}}{\#\left\{j:W_{j}^{(b)}\geq t\right\}}\right)\geq FDR(t).$$

$$FDR_{B}(t)$$

Theoretical result

Theorem (FDR control for single missKnockoff)

missKnockoff procedure with single imputation from $p(X_{mis}|X_{obs})$ controls FDR at level q.

Theorem (FDR estimation for multiple missKnockoff)

Consider the single missKnockoff procedure, which rejects $H_{0j}: \beta_j = 0$ if $W_j > t$, and let

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Then for the ${\it multiple\ missKnockoffs}$ procedure with variable importance statistics $\{W_j^b\}$:

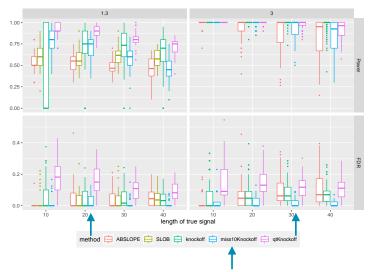
$$\mathbb{E}\left(\frac{1}{B}\sum_{b=1}^{B}\frac{\#\left\{j:W_{j}^{(b)}\leq-t\right\}}{\#\left\{j:W_{j}^{(b)}\geq t\right\}}\right)\geq FDR(t)\,.$$

- $\widehat{FDR}_B(t)$ for missKnockoff with B bootstrap is an upwards biased estimator of FDR(t), with variance which diminishes with B (for t > 0 and B > 1).
- It holds almost surely that $\lim_{B\to\infty}\widehat{FDR}_B(t)=\mathbb{E}\left[\widehat{FDR}(t)|X_{\rm obs},y\right]$, the right side = the conditional expectation of estimated false discovery proportion provided by the single missKnockoff procedure.



Simulation results (few competitors)

n=p=500 Signal strength $1.3\sqrt{2\log p}$ (left) / strong $3\sqrt{2\log p}$ (right).



General conclusion

- Comprehensive framework for dealing with missing values from estimation to model selection for logistic regression model
 - Methodology, algorithm, simulations
 - R package misaem
- New methods for high-dimensional model selection with FDR control (parametric/ non-parametric)
 - Methodology, algorithm, theoretical results, simulations
 - R package ABSLOPE
- Analysis of hospital dataset (TraumaBase)
 - Improve health care (interpretability, transparency)
 - Results presented at French Society of Anesthesia & Intensive Care Medicine (SFAR) meeting
 - TraumaBase mobile application under development



Screenshots of TraumaBase application



Perspectives

- Extension to deal with mixed incomplete covariates with both continuous and categorical, ordinal and binary data (ongoing)
 - General location model (Zhao and Udell, 2019)
 - Gaussian copula (Zhao and Udell, 2019)
- Extension of ABSLOPE (ordered l₁ penalty) in generalized linear models
- Extension to another missing mechanism (MNAR)
- Testing unconditional independence (Candes et al., 2018) with missing values (to improve the power for missKnockoff)

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Malgorzata Bogdan





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Asaf Weinstein



Veronika Rockova



Sophie Hamada





Tobias Gauss

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Thanks for your attention!

Merci

Appendix 1: Logistic regression with missing covariates

Variance estimation

Observed Fisher information matrix (FIM) $wrt \beta$

$$\mathcal{I}(\theta) = -\frac{\partial^2 \ell(\theta; X_{\text{obs}}, y)}{\partial \theta \partial \theta^T}.$$

Variance estimation

Observed Fisher information matrix (FIM) $wrt \beta$

$$\mathcal{I}(\theta) = -\frac{\partial^2 \ell(\theta; X_{\text{obs}}, y)}{\partial \theta \partial \theta^T}.$$

Louis formula

$$\begin{split} \mathcal{I}(\theta) &= -\mathbb{E}\left(\frac{\partial^{2}\ell(\theta;X,y)}{\partial\theta\partial\theta^{T}}\big|X_{\mathrm{obs}},y;\theta\right) \\ &- \mathbb{E}\left(\frac{\partial\ell(\theta;X,y)}{\partial\theta}\frac{\partial\ell(\theta;X,y)^{T}}{\partial\theta}\big|X_{\mathrm{obs}},y;\theta\right) \\ &+ \mathbb{E}\left(\frac{\partial\ell(\theta;X,y)}{\partial\theta}\big|X_{\mathrm{obs}},y;\theta\right)\mathbb{E}\left(\frac{\partial\ell(\theta;X,y)}{\partial\theta}\big|X_{\mathrm{obs}},y;\theta\right)^{T}. \end{split}$$

Given the MH samples of unobserved data $(X_{i,\mathrm{mis}}^{(m)}, 1 \leq i \leq n, 1 \leq m \leq M)$, and the SAEM estimate $\hat{\pmb{\theta}}$ \Rightarrow Estimate FIM by empirical means.

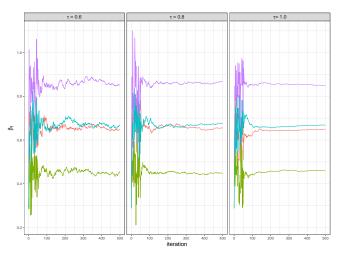
Simulation study: SAEM behavior

Step size : $\gamma_k = (k - k_1)^{-\tau}$

 $k_1 = 50$ and $\tau = (0.6, 0.8, 1.0)$.

N = 1000, p = 5, percentage of missingness= 10%

4 repetitions of simulations and 500 iterations:

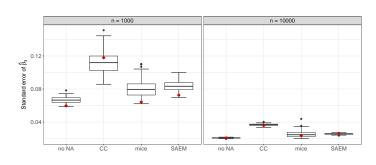




Method comparison: coverage

Table: Coverage (%) for $n=10\,000$, calculated over 1000 simulations.

parameter	no NA	CC	mice	SAEM
β_0	95.2	94.4	95.2	94.9
β_1	96.0	94.7	93.9	95.1
β_2	95.5	94.6	94.0	94.3
β_3	94.9	94.3	86.5	94.7
β_4	94.6	94.2	96.2	95.4
β_5	95.9	94.4	89.6	94.7



Mo

Model selection results

Table: For data with or without correlation, percentage of times that different criterion selects the correct true model (C), overfit (O), i.e. select more variables, and underfit (U) select less variables.

	Non-Correlated			l Co	Correlated		
Criterion	C	Ο	U	C	Ο	U	
$\overline{AIC_{obs}}$	60	40	0	65	32	3	
AIC_{orig}	73	27	0	75	20	5	
AIC_{cc}	67	32	1	77	16	7	
BIC_{obs}	92	3	5	94	2	4	
BIC_{orig}	96	2	2	93	0	7	
BIC_{cc}	79	1	20	91	0	9	



Method comparison: execution time

Table: Comparison of execution time between no NA, MCEM, mice, and SAEM with n=1000 calculated over 1000 simulations.

Execution time (seconds)	no NA	MCEM	mice	SAEM
min	2.87×10^{-3}	492	0.64	9.96
mean	4.65×10^{-3}	773	0.70	13.50
max	43.50×10^{-3}	1077	0.76	16.79

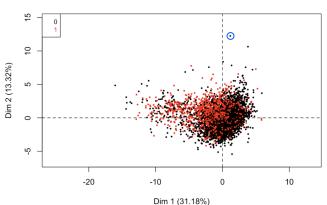
Exploration of dataset

Data preprocessing \Rightarrow 6384 patients in the dataset.

Clinical experience ⇒ **14 influential quantitative measurements** Based on **penalized observed log-likelihood**:

- \Rightarrow Observations resulting in a very small value of the log-likelihood.
- \Rightarrow wrong records

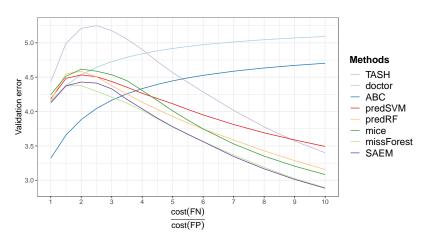
Individuals factor map (PCA)





Predictive performance

Random split: training set (70%) + test set (30%) (repeated 15 times)



Appendix 2: ABSLOPE

False discovery rate control

In an orthogonal design:

$$\tilde{y} = X^T y = X^T X \beta + X^T \varepsilon = \beta + X^T \varepsilon \sim \mathcal{N}(\beta, \sigma^2 I_p).$$

Selecting model \Leftrightarrow multiple tests: $H_{0,j}: \beta_j = 0$. To control the FDR at level q, (Benjamini and Hochberg, 1995)

- ② corresponding hypotheses $H_{(1)}, \cdots, H_{(p)}$
- 3 rejects all $H_{(i)}$ for which

$$i \le i_{BH} = \max \left\{ i : \frac{|\tilde{y}|_{(i)}}{\sigma} \ge \phi^{-1} (1 - q_i) \right\}, \quad q_i = \frac{iq}{2p},$$

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$$i \le i_{BH} = \max \left\{ i : \frac{|\tilde{y}|_{(i)}}{\sigma} \ge \phi^{-1} (1 - q_i) \right\}, \quad q_i = \frac{iq}{2p},$$

For SLOPE, if we set $\lambda_{BH}(j) = \phi^{-1}(1 - q_j)$, $q_j = \frac{jq}{2p}$, then

$$FDR = \mathbb{E}\left[\frac{\# \text{False rejections}}{\# \text{Rejections}}\right] \leq q \frac{p_0}{p}, \quad p_0 = \# \text{ true null hypotheses}$$

SLOPE -> ABSLOPE

Proposition

Assume that a random variable $z = (z_1, z_2, \dots, z_p)$ has a SLOPE prior:

$$p(z \mid \sigma^2; \lambda) \propto \prod_{j=1}^p \exp\left\{-\frac{1}{\sigma} \lambda_{r(z,j)} |z_j|\right\},$$

and then define $\beta = W^{-1}z = (\frac{z_1}{w_1}, \cdots, \frac{z_p}{w_p})$. Finally the prior of β corresponds to ABSLOPE

$$p(\beta \mid \gamma, c, \sigma^2; \lambda) \propto c^{\sum_{j=1}^p \mathbb{I}(\gamma_j = 1)} \prod_j \exp\left\{-\frac{w_j}{\beta_j} \left| \frac{1}{\sigma} \lambda_{r(\mathbf{W}\beta, j)} \right.\right\},$$

Details of Simulation step

$$\begin{split} X_{\mathrm{mis}} &\sim \mathrm{p}(X_{\mathrm{mis}} \mid \gamma, c, y, X_{\mathrm{obs}}, \beta, \sigma, \theta, \mu, \Sigma) \\ &= \mathrm{p}(X_{\mathrm{mis}} \mid y, X_{\mathrm{obs}}, \beta, \sigma, \mu, \Sigma) \\ &\propto \mathrm{p}(y \mid X_{\mathrm{obs}}, X_{\mathrm{mis}}, \beta, \sigma) \, \mathrm{p}(X_{\mathrm{mis}} \mid X_{\mathrm{obs}}, \mu, \Sigma). \end{split}$$

Proposition

Let \mathcal{M} be the set containing indexes for missing covariates and \mathcal{O} for the observed ones. Assume that $p(x_{\text{obs}}, x_{\text{mis}}; \Sigma, \mu) \sim \mathcal{N}(\mu, \Sigma)$ and let $y = x\beta + \varepsilon$ where $\varepsilon \sim N(0, \sigma^2)$. For all the indexes of the missing covariates $i \in \mathcal{M}$, we denote:

$$m_i = \sum_{q=1}^{p} \mu_i s_{iq}, \quad u_i = \sum_{k \in \mathcal{O}} x_{\text{obs}}^k s_{ik}, \quad r = y - x_{\text{obs}} \beta_{\text{obs}}, \quad \tau_i = \sqrt{s_{ii} + \beta_i^2 / \sigma^2},$$

with s_{ij} elements of Σ^{-1} and β_{obs} the observed elements of β .

Let $\tilde{\mu} = (\tilde{\mu}_i)_{i \in \mathcal{M}}$ be the solution of the following system of linear equations:

$$\frac{r\beta_i/\sigma^2 + m_i - u_i}{\tau_i} - \sum_{\substack{i \in \mathcal{M} \ i \neq i}} \frac{\beta_i\beta_j/\sigma^2 + s_{ij}}{\tau_i\tau_j} \tilde{\mu}_j = \tilde{\mu}_i \ , \quad \textit{for all } i \in \mathcal{M},$$

and let B be a matrix with elements:
$$B_{ij} = \begin{cases} \frac{\beta_i \beta_j / \sigma^2 + s_{ij}}{\tau_i \tau_j}, & \text{if } i \neq j \\ 1, & \text{if } i = j \end{cases}$$
, then for

$$z = (z_i)_{i \in \mathcal{M}}$$
 where $z_i = \tau_i x_{\text{mis}}^i$ we have
 $z \mid x_{\text{obs}}, y; \Sigma, \mu, \beta, \sigma^2 \sim N(\tilde{\mu}, B^{-1})$.

Stochastic Approximation step

When step-size $\eta_t = 1 \Leftrightarrow \text{Stochastic EM (SEM)}$ Estimation \Leftrightarrow maximizing $\ell_{\text{comp}}\Big|_{X_{\text{mis}}^t, \gamma^t, c^t}$ Update β for an example:

$$\beta^{t} = \arg\max_{\beta} -\frac{1}{2(\sigma^{t-1})^{2}} \|y - X^{t}\beta\|^{2} - \frac{1}{\sigma^{t-1}} \sum_{j=1}^{p} w_{j}^{t} |\beta_{j}| \lambda_{r(W^{t}\beta, j)}$$

where $X^t = (X_{\text{obs}}, X_{\text{mis}}^t)$.

 \Leftrightarrow Solution of SLOPE, given W^t , X_{mis}^t and σ^{t-1} .

 \Rightarrow proximal gradient.



Basic Idea of proximal gradient

SLOPE is a convex optimization problem of the form

$$\min f(\beta) = g(\beta) + h(\beta)$$

g: smooth and convex h: convex but not smooth At each iteration, compute a local approximation to g:

$$g(\beta^t) + \langle \nabla g(\beta^t), x - \beta^t \rangle + \frac{1}{2r} ||x - \beta^t||^2,$$

where r is a step size. Then update β^{t+1}

$$\beta^{t+1} = \underset{x}{\arg\min} g(\beta^t) + \langle \nabla g(\beta^t), x - \beta^t \rangle + \frac{1}{2r} \|x - \beta^t\|^2 + h(x)$$

$$= \underset{x}{\arg\min} \frac{1}{2r} \|(\beta^t - t\nabla g(\beta^t)) - x\|^2 + h(x)$$

$$= \underset{x}{\arg\min} \frac{1}{2r} \|(\beta^t - t\nabla g(\beta^t)) - x\|^2 + h(x)$$

The prox of l_1 norm is given by entry-wise soft thresholding.

Model selection results 0 True False True model Positive Negative 1 (TP) (FN) False True Positive Negative (FP) (TN)

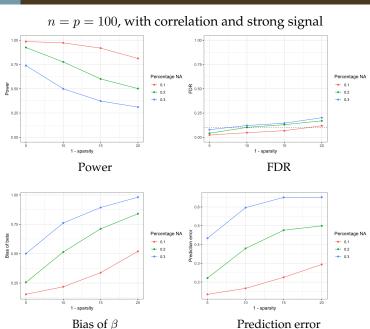
• FDR =
$$\frac{FN}{FN+TN}$$
;

• Power =
$$\frac{TP}{TP+FN}$$
;

• Relative MSE =
$$\frac{\|\hat{\beta} - \beta\|^2}{\|\beta\|^2}$$
.



Effect of missing percentage



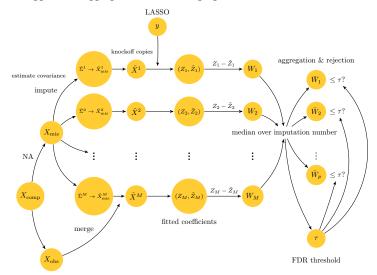
Prediction error

Appendix 3: missKnockoff

missKnockoff: handling missing values

Contributions:

- Combine multiple imputation ⇒ single knockoff on each imputed dataset values
- Suggest new aggregation rules (averaging the cases)





missKnockoff: handling missing values

Input: $X = (X_{mis}, X_{obs})$ (rows can have different pattern of missing values);

for $b = 1, 2, \cdots, B$ do

(Bootstrap: reflect sampling variability in covariance matrix estimate)

- Bootstrap X with missing values.
- On bootstrap samples, estimate the covariance (Schneider, 2001; Lounici et al., 2014):

$$\hat{\Sigma}^b = (\hat{\delta}^{-1} - \hat{\delta}^{-2}) \operatorname{diag}(\hat{\Sigma}_n) + \hat{\delta}^{-2}\hat{\Sigma}_n,$$

with $\hat{\delta}$ the proportion of observed entries and $\hat{\Sigma}_n$ the linear shrinkage estimation on empirical covariance of initially imputed dataset by 0.

(Generate multiple knockoff and compute importance measures)

- With $\hat{\Sigma}^b$, impute missing values \hat{X}^b_{mis} from p $(X_{\mathrm{mis}} \mid X_{\mathrm{obs}})$ and generate knockoff copies \tilde{X}^b from p $\left(\tilde{X} \mid X = \left(X_{\mathrm{obs}}, \hat{X}^b_{\mathrm{mis}}\right)\right)$.
- On the set $(y, \hat{X}^{(b)}, \tilde{X}^{(b)})$, use LASSO to obtain fitted coefficient vectors and statistics: $Z_j^{(b)} = \left| \hat{\beta}_j^{(b)} \right|, \quad \tilde{Z}_j^{(b)} = \left| \hat{\beta}_{j+p}^{(b)} \right|.$
- 3 Calculate variable importance $W_{j}^{(b)}=Z_{j}^{(b)}-\tilde{Z}_{j}^{(b)}$, $j=1,2,\cdots,p$.

(Aggregation by averaging the cases)

- $\textbf{ 1} \text{ Estimate the knockoff threshold: } \tau = \min \left\{ t: \frac{1}{B} \sum\nolimits_{b=1}^{B} \frac{\# \left\{ j: W_{bj} \leq -t \right\} + c}{\# \left\{ j: W_{bj} \geq t \right\} \vee 1} \leq q \right\}.$
- 2 Calculate the median of $\{W_{mj}\}$ over $b=1,2,\cdots,B$ to obtain \bar{W}_j .

if $\bar{W}_i < \tau$ then

Reject j-th variable.

Output: Indexes for model selection $\{j : \bar{W}_j > \tau\}$.

Theoritical result

Theorem (FDR control for single missKnockoff)

missKnockoff procedure with single imputation from $p(X_{mis}|X_{obs})$ controls FDR at the level q.

Sketch of proof:

If we generate values for missing covariates with:

$$\hat{X}_{\text{mis}} \sim p(X_{\text{mis}} \mid X_{\text{obs}}),$$

$$\Rightarrow (X_{\text{obs}}, \hat{X}_{\text{mis}}) \stackrel{d}{=} X$$
.

$$\Rightarrow (X_{\text{obs}}, \hat{X}_{\text{mis}}, \tilde{X})_{\text{swap}(S)} \stackrel{d}{=} (X, \tilde{X}).$$

- \Rightarrow Design matrix with imputed missing values satisfies the exchangeability condition.
- ⇒ it satisfies the definition of model-X knockoff.
- \Rightarrow FDR control.